

# Hypothesis testing and OLS Regression

NIPFP

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# Overview

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Model Specification

## The OLS estimator continued

- As we discussed yesterday, the OLS estimator is a means of obtaining good estimates of  $\beta_1$  and  $\beta_2$ , for the relationship 
$$Y = \beta_1 + \beta_2 X_1 + \epsilon$$
- Let us now move towards drawing inferences about the true  $\beta_1$  and  $\beta_2$ , given our estimates  $\hat{\beta}_1$  and  $\hat{\beta}_2$ . This requires making some valid assumptions about  $X_i$  and  $\epsilon$ . These assumptions also evoke certain useful statistical properties of OLS, as contrasted with the purely numerical properties which we saw yesterday.

# Assumptions of OLS regression

- Assumption 1: The regression model is linear in the parameters.  $Y = \beta_1 + \beta_2 X_i + u_i$ . This does not mean that  $Y$  and  $X$  are linear, but rather that  $\beta_1$  and  $\beta_2$  are linear.

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- Assumption 2:  $X$  values are fixed in repeated sampling.
- Assumption 3: The expectation of the disturbance  $u_i$  is zero. Thus, the distribution of  $u_i$  given a value of  $X_i$  (in the population) is symmetric around its mean. (Show figure).

- Assumption 4: The variance of  $u_i$  is the same for all observations, i.e. in the above distribution, the distribution of  $u_i$  given each value of  $X_i$  has the same variance. This is an important property called **homoskedasticity**.

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- Assumption 5: There is no correlation between the  $u_i$  (disturbances) of different observations. This is called **auto-correlation** or **serial-correlation**. It is seen more in time series analysis than cross-sectional analysis.
- Assumption 6: The covariance between  $u_i$  and  $X_i$  is zero. Intuitively, since we express  $Y$  as a sum of  $X_i$  and  $U_i$ , if these two are correlated, then we must include a covariance term in the summation. So, by assumption, the covariance = 0.

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- Assumption 9: The regression model is correctly specified. There is no **specification error**, there is no **bias**
- Assumption 10: There is no perfect **multicollinearity**, no two  $X_i$  values can be expressed as a perfect linear combination of each other.

# Statistical properties that emerge from the assumptions

## Theorem (Gauss Markov Theorem)

*In a linear model in which the errors have expectation zero and are uncorrelated and have equal variances, a best linear unbiased estimator (BLUE) of the coefficients is given by the least-squares estimator*

## BLUE estimator

- Linear: It is a linear function of a random variable
- Unbiased: The average or expected value of  $\hat{\beta}_2 = \beta_2$
- Efficient: It has minimum variance among all other estimators
- However, not all ten classical assumptions have to hold for the OLS estimator to be B, L or U.

# Interpreting an OLS coefficient/hypothesis testing

Call:

```
lm(formula = y ~ x)
```

Residuals:

	Min	1Q	Median	3Q	Max
	-2.77652	-0.77009	0.06778	0.60591	3.44186

Coefficients:

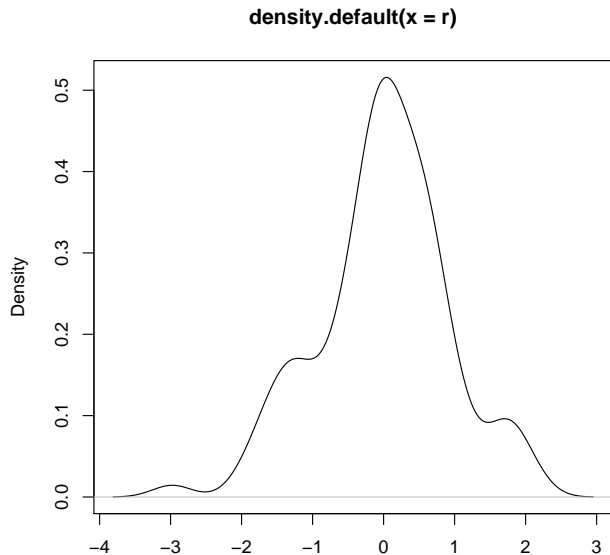
	Estimate	Std. Error	t value	Pr(> t )
(Intercept)	1.7816	0.2132	8.355	4.41e-13
x	3.0457	0.0398	76.531	< 2e-16

Residual standard error: 1.087 on 98 degrees of freedom

Multiple R-squared: 0.9835, Adjusted R-squared: 0.98

F-statistic: 5857 on 1 and 98 DF, p-value: < 2.2e-16

# Interpreting an OLS coefficient/hypothesis testing





# Algebraic notation of the coefficient/estimator

- The least squares result is obtained by minimising  $(y - \beta_1 X)'(y - \beta_1 X)$
- Expanding,  $y'y - \beta_1' X'y - y'X\beta_1 + \beta_1' X'X\beta_1$
- Differentiating with respect to  $\beta_1$ , we get  $-2X'y + 2X'X\beta_1 = 0$
- Or  $X'X\beta_1 = X'y$
- Or  $\beta_1 = (XX')^{-1}X'y$

# Properties of the estimators

## Testing a hypothesis about the estimator

We know that:

$$\begin{aligned}\hat{\beta} &= (X'X)^{-1}X'Y \\ &= (X'X)^{-1}X'(X\beta + \epsilon) \\ &= \beta + (X'X)^{-1}X'\epsilon\end{aligned}$$

And now take the expectation:

$$\begin{aligned}E[\hat{\beta}] &= \beta + (X'X)^{-1}X'E[\epsilon] \\ &= \beta + 0 \\ &= \beta\end{aligned}$$

- So far, we have not used the normality of residual assumption to derive any of our results.
- This assumption, however, is useful to test a hypothesis about an estimator.
- This allows us to test a hypothesis about  $\hat{\beta}$ .

## Theorem

$$\hat{\beta} \sim \mathcal{N}\left(\beta, \frac{\sigma^2(X'X)^{-1}}{n}\right)$$

## Proof.

- Either with the assumption that  $\varepsilon \sim \mathcal{N}(0, \sigma^2)$
- Or asymptotically by TCL



## Some useful numbers: $R^2$

- $R^2$ , or the coefficient of goodness-of-fit of a regression, measures the extent of overlap between the variables Y and X. (Show Venn diagram). Since it is a ratio variable, it lies between 0 and 1.
- Technically, it can be expressed as:
  - $\sum Y_i - \bar{Y}^2 = \beta_2^2 \sum X_i - \bar{X}^2 + \sum u_i^2$ , or
  - $\text{TSS} = \text{ESS} + \text{RSS}$
  - $R^2 = \text{ESS}/\text{TSS}$
- This is a useful number, but it must be kept in mind that it is not the best/only indicator of how “good” the regression is.
- Spurious regression: Two numbers that are statistically, but not causally related.
- As you add more variables to the regression, the  $R^2$  only increases!

An example with R: Dangers of  $R^2$ 

Call:

```
lm(formula = x ~ y)
```

Residuals:

Min	1Q	Median	3Q	Max
-4.8300	-2.6357	-0.1053	2.7757	5.3684

Coefficients:

	Estimate	Std. Error	t value	Pr(> t )
(Intercept)	4.6446	0.3189	14.567	<2e-16
y	-0.1890	0.3432	-0.551	0.583

Residual standard error: 3.024 on 98 degrees of freedom

Multiple R-squared: 0.003084, Adjusted R-squared: -0.00181

F-statistic: 0.3032 on 1 and 98 DF, p-value: 0.5832

An example with R: Dangers of  $R^2$ 

Call:

`lm(formula = x ~ y + m)`

Residuals:

Min	1Q	Median	3Q	Max
-4.8994	-2.7182	-0.2155	2.8353	5.5601

Coefficients:

	Estimate	Std. Error	t value	Pr(> t )
(Intercept)	4.5328	0.3218	14.084	<2e-16
y	-0.1355	0.3409	-0.397	0.6919
m	-0.5234	0.2976	-1.759	0.0817

Residual standard error: 2.992 on 97 degrees of freedom

Multiple R-squared: 0.0339, Adjusted R-squared: 0.01

F-statistic: 1.702 on 2 and 97 DF, p-value: 0.1878

An example with R: Dangers of  $R^2$ 

Call:

lm(formula = x ~ y + m + z)

Residuals:

Min	1Q	Median	3Q	Max
-4.9964	-2.4296	-0.3385	2.6638	5.7291

Coefficients:

	Estimate	Std. Error	t value	Pr(> t )
(Intercept)	4.5316	0.3225	14.052	<2e-16
y	-0.1402	0.3417	-0.410	0.683
m	-0.4979	0.2999	-1.660	0.100
z	-0.2285	0.2904	-0.787	0.433

Residual standard error: 2.998 on 96 degrees of freedom

Multiple R-squared: 0.04009, Adjusted R-squared: 0.0

F-statistic: 1.336 on 3 and 96 DF, p-value: 0.2671

## Some useful numbers: Adjusted $R^2$

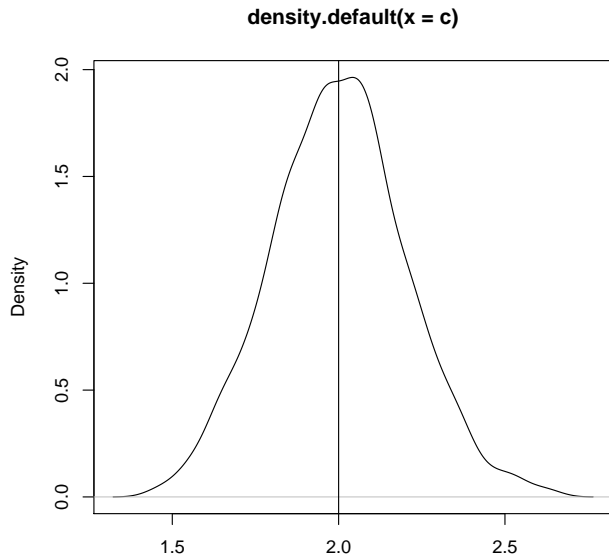
- This helps reduce the danger of  $R^2$ , as it adjusts the value of  $R^2$  to the number of independent variables in the model.
- $\bar{R}^2 = 1 - \frac{n-1}{n-k}(1 - R^2)$
- But it is still related to  $R^2$



## Some useful numbers: Akaike Information Criterion

- Another way of measuring goodness of fit, adjusted for the number of variables
- $AIC = e^{2k/n}RSS/n$
- Lower AIC is better, and  $2k/n$  can be interpreted as the “penalty factor”.

# A Monte-Carlo simulation



## Some issues in model specification

- Scaling and units of measurement: Interpreting  $\hat{\beta}_1$  and  $\hat{\beta}_2$  when  $X$  is expressed in different ways
- Standardised coefficients
- Various functional forms: Linear, log-linear, lin-log etc

Thank you.